



JIALE CHEN

Email: jiale.chen01@universitadipavia.it

Email: jiale.chen@cnao.it

LinkedIn: www.linkedin.com/in/jiale-chen-intl

Address: 27100 Pavia, Italy

SKILLS

Languages: Mandarin (Native), English (Advanced), German (Good)

Programming Languages: Python, MATLAB, C++, Kotlin, Java, GLSL

Technical Domains: ML, NLP, GNNs, XR, CAD, IIoT, Digital Twins, Computer Vision

Frameworks & Tools: Unity, Django, PyTorch, Docker, OpenCV, NumPy, ROS

Software Engineering: Git, Poetry, Anaconda, CI/CD (GitLab CI), pytest, mypy, pre-commit

Document Preparation: Microsoft Office Suite, \LaTeX , Markdown

EDUCATION

Doctor of Philosophy <i>Bioengineering, Bioinformatics and Health Technologies</i> Università di Pavia	Oct. 2025 – present Pavia, Italy
Master of Science <i>information and Communication Engineering</i> Technische Universität Darmstadt	Nov. 2021 – Nov 2024 Darmstadt, Germany
Bachelor of Eng. <i>Major: Electrical Engineering and its Automation, Minor: German</i> China University of Mining and Technology	Sep. 2016 – Jun. 2020 Jiangsu, China
Exchange Program <i>Major: Electrical and Electronic Engineering</i> University of Nottingham	Nov. 2018 – Mar. 2019 Nottingham, UK

WORK EXPERIENCE

Clinical Bioengineer Fondazione CNAO / Clinical Bioengineering <ul style="list-style-type: none">Develop VR training system, targeted for patients empowerment in Upright particle therapy.	October 2025 – present Pavia, Italy
Feature Developer TU Darmstadt / ETA Fabrik <ul style="list-style-type: none">Developed and maintained communication-protocol modules for the ETA-Nexus industrial automation platform.Designed and tested Python-based backend components, improving reliability and extensibility of the connection manager.	May 2025 – Sept. 2025 Darmstadt, Germany
Connected Infotainment Internship AUDI AG <ul style="list-style-type: none">Refined and expanded technical requirement documentation for the Series-Development Phase of Managed Device Management (MDM).Consolidated and documented requirements for the PoC of the Connected Streaming App.Conceptualized an automated testing solution for production apps, structured detailed technical specifications.Enhanced internal Media Tester App, focusing on automation, error detection, and UI improvements.Designed automated test reporting and created test scenarios using FFmpeg to simulate and validated unsupported, destroyed, and various error media files conditions.Optimized media playback logic for multi-screen environments and global audio control.	Oct. 2024 – Mar. 2025 Ingolstadt, Germany
Student Research Assistant TU Darmstadt / SPG Group	May 2024 – Jul. 2024 Darmstadt, Germany

- Provided tutoring for Signal Processing Lab, assisting students with lab exercises and concepts, evaluated submitted reports for grading.

Student Research Assistant

Jun. 2023 – Jul. 2024

TU Darmstadt / NTS Group

Darmstadt, Germany

- Validated anomaly detection methods in communication systems based on Graph theory.
- Developed anomaly detection and sequence-targeted prediction model based on Transformer model.

Infotainment Product Engineer

Oct. 2020 – Aug. 2021

Stellantis (PSA) Group

Shanghai, China

- Led the development and integration of the In-Vehicle Infotainment (IVI) Module, managing cross-functional collaboration between hardware and software suppliers to ensure seamless system integration.
- Coordinated closely with the testing team to oversee module validation and quality assurance on both test benches and vehicle prototypes.
- Managed module configuration and deployment across multiple carline projects, ensuring compliance with project timelines and technical requirements.

PROJECTS AND RESEARCH

Praktikum Visual Computing | *Python, Pytorch*

2025

Fraunhofer IGD / TU Darmstadt

- **Title: Mixture-of-Experts Neural Cellular Automata (NCA) for Abdominal CT Segmentation.**
- Designed and implemented multiple NCA-based segmentation backbones (full backbone, shared-convolution, shared-conv + dense) for 512×512 abdominal CT data.
- Developed and compared a variety of gating strategies (learning-based, averaging-based; level-wise vs. step-wise) to control expert selection and aggregation.
- Investigated different MoE placements (all-level vs. top-level) to balance segmentation accuracy and computational efficiency.
- Developed reproducible PyTorch pipelines and evaluation metrics for CT-1k, enabling systematic benchmarking; two architectures achieved superior performance over the baseline.

Master Thesis | *Python, Pytorch*

2024

Technische Universität Darmstadt

- **Title: Model-Assisted DL for Resource Allocation in Cellular Networks with Stochastic Channel Models.**
- Developed an unrolled GCN-DL framework combining traditional model-based optimization (WMMSE) problem to solve resource allocation in MU-MIMO systems.
- Focused on solving the non-convex mathematical problem, optimizing the weighted sum rate through iterative optimization and structured neural networks (Stochastic WMMSE).
- Applied stochastic channel models to simulate dynamic wireless environments and evaluated model performance on varying channel sequences.

Project Seminar | *Python, Pytorch, Matlab*

2023

Technische Universität Darmstadt

- Reproduction: Vision-Assisted 3-D Predictive Beamforming for Green UAV-to-Vehicle Communications.
- Led a team to reproduce and validate the mathematical models and algorithms from the original research paper, ensuring alignment with theoretical and experimental results.

Project Seminar | *Python, Django*

2022

Technische Universität Darmstadt

- **Title: Implementation of a 5G Data Tracing APP.**
- Independently developed a web-based application for 5G network data tracing, including data collection, processing, and visualization.

Bachelor Thesis | *Python, ROS*

2020

China University of Mining and Technology

- **Title: Robotic Navigation Study based on ROS and Machine Learning.**
- Conducted an in-depth theoretical study on robotic navigation systems, focusing on various sensors, including LiDAR and cameras, for environment perception and mapping.
- Simulated end-to-end deep learning model for robot mapping using camera inputs.
- Implemented a practical SLAM-based mapping and navigation system on a ROS mobile robot, successfully navigating a dormitory corridor.